## Nested Krylov methods for shifted linear systems

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## Motivation (1/3)Full-waveform inversion

PDE-constrained optimization:

$$\min_{\boldsymbol{\rho}(\mathbf{x}), \boldsymbol{c}_{\boldsymbol{\rho}}(\mathbf{x}), \boldsymbol{c}_{s}(\mathbf{x})} \| \mathbf{u}_{sim} - \mathbf{u}_{meas} \|,$$



where in our application:

- **u**<sub>sim</sub> is the (numerical) solution of the elastic wave equation,
- **u**<sub>meas</sub> is obtained from measurements,
- $\rho$ ,  $c_p$ ,  $c_s$  are properties of earth layers we are interested in.

The modeling is done in frequency-domain.



## Motivation (2/3)The discrete forward model

An FEM discretization of the time-harmonic, inhomogeneous elastic wave equation at multiple frequencies  $\omega_k$  is given by:

$$(K + i\omega_k C - \omega_k^2 M)\mathbf{u}_k = \mathbf{s}, \quad k = 1, ..., N,$$

where

- K, C, M are sparse and symmetric,
- s usually models a point source,
- we need to compute the displacement vector u<sub>k</sub> for multiple frequencies (shifts) ω<sub>k</sub>.



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## Motivation (3/3) Multi-shift Krylov methods

We can re-formulate the previous problem to:

$$\begin{bmatrix} \begin{pmatrix} iC & K \\ I & 0 \end{pmatrix} - \omega_k \begin{pmatrix} M & 0 \\ 0 & I \end{pmatrix} \end{bmatrix} \begin{pmatrix} \omega_k \mathbf{u}_k \\ \mathbf{u}_k \end{pmatrix} = \begin{pmatrix} \mathbf{s} \\ 0 \end{pmatrix},$$

which is of the form:

$$(\mathcal{A} - \omega_k \mathcal{M})\mathbf{x}_k = \mathbf{b}$$

Shift-invariance of Krylov subspaces:

 $\mathcal{K}_m(\mathcal{A}, \mathbf{r}_0) \equiv \operatorname{span}\{\mathbf{r}_0, \mathcal{A}\mathbf{r}_0, ..., \mathcal{A}^{m-1}\mathbf{r}_0\} = \mathcal{K}_m(\mathcal{A} - \omega I, \mathbf{r}_0)$ 

is challenging to *preserve* when preconditioning!



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## Preconditioners for shifted linear systems

2004 (Complex) shifted Laplace preconditioner:

$$\mathcal{P} = (\mathcal{A} - \tau \mathcal{M}), \quad \tau \approx \{\omega_1, ..., \omega_N\}$$

2007 Many shifted Laplace preconditioners:

$$\mathcal{P}_j = (\mathcal{A} - \tau_j \mathcal{M})$$

2013 Polynomial preconditioners [Plenary talk at PRECON13]

2014 Question: Can we use a Krylov method as preconditioner? → Nested Krylov methods



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## Outline



Inner-outer Krylov methods for shifted linear systems







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The generalized shifted Laplace preconditioner,

$$\mathcal{P} = (\mathcal{A} - \tau \mathcal{M}), \quad \tau \in \mathbb{C},$$
 (\*)

has two benefits:

- it transforms our problem to shifted linear systems and, hence, enables the benefits of shift-invariant Krylov spaces,
- it maps the original spectrum to circles of known center and radius.

Moreover, (\*) is easy to apply because  $\tau \in \mathbb{C}$  leads to a damped problem  $\rightsquigarrow$  multigrid works!



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For  $\mathcal{P} = (\mathcal{A} - \tau \mathcal{M})$ , the following relation holds:

$$(\mathcal{A} - \omega_k \mathcal{M}) \mathcal{P}_k^{-1} = \mathcal{A} \mathcal{P}^{-1} - \eta_k(\omega) \mathbf{I}, \qquad (**)$$

with

• 
$$\mathcal{P}_k^{-1} = \frac{\tau}{\tau - \omega_k} \mathcal{P}^{-1}$$
  
•  $\eta_k = \omega_k / (\omega_k - \tau)$ 

•  $\tau$  is a free parameter (seed shift)

For the spectrum of the RHS in (\*\*), we see:

$$\sigma\left(\mathcal{AM}^{-1}\right) \ni \lambda \mapsto \frac{\lambda}{\lambda - \tau} - \eta_k$$



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## The shifted Laplacian - Spectral analysis

Compare:



Open question: What's the optimal  $\tau$  for equidistantly spaced frequencies  $\omega_1, ..., \omega_N$  ???

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## The shifted Laplace preconditioner and its relation to Möbius transformations

#### Inner-outer Krylov methods for shifted linear systems







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Krylov methods for shifted linear systems

Solve the preconditioned shifted problem,  $\mathcal{B} := \mathcal{AP}^{-1}$ ,

$$(\mathcal{B} - \eta_k I) \mathbf{x}_k = \mathbf{b}, \quad k = 1, ..., N,$$

$$\mathcal{K}_k(\mathcal{B},\mathbf{r}_0) = \mathcal{K}_k(\mathcal{B}-\eta I,\mathbf{r}_0) \quad \forall \eta.$$





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## Inner method: multi-shift FOM

Classical result: In FOM, the residuals are:

$$\mathbf{r}_j = \mathbf{b} - \mathcal{B}\mathbf{x}_j = \dots = -h_{j+1,j}\mathbf{e}_j^T\mathbf{y}_j\mathbf{v}_{j+1}.$$

Thus, for the shifted residuals it holds:

$$\mathbf{r}_{j}^{(\eta)} = \mathbf{b} - (\mathcal{B} - \eta I)\mathbf{x}_{j}^{(\eta)} = ... = -h_{j+1,j}^{(\eta)}\mathbf{e}_{j}^{\mathsf{T}}\mathbf{y}_{j}^{(\eta)}\mathbf{v}_{j+1}.$$

 $\mathbf{r}_i^{(\eta)} = \gamma \mathbf{r}_j,$ 

Hence, we obtain collinear residuals,

with factor 
$$\gamma = y_j^{(\eta)}/y_j$$
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V. Simoncini, *Restarted full orthogonalization method for shifted linear systems*. BIT Numerical Mathematics, 43 (2003).



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Hence, we obtain collinear residuals,

$$\mathbf{r}_{j}^{(\eta)}=\gamma\mathbf{r}_{j}$$

with factor  $\gamma = y_j^{(\eta)}/y_j$ .

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Use flexible GMRES in the outer loop,

$$(\mathcal{B}-\eta I)\widehat{V}_m=V_{m+1}\underline{H}_m^{(\eta)},$$

where one column yields:

$$(\mathcal{B} - \eta I) \underbrace{\mathcal{P}(\eta)_j^{-1} \mathbf{v}_j}_{\text{inner loop}} = V_{m+1} \underline{\mathbf{h}}_j^{(\eta)}, \quad 1 \leq j \leq m.$$

Recap: The "inner loop" is the truncated solution of  $(\mathcal{B} - \eta I)$  with right-hand side  $\mathbf{v}_i$  using msFOM.



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The inner residuals are:

$$\mathbf{r}_{j}^{(\eta)} = \mathbf{v}_{j} - (\mathcal{B} - \eta I)\mathcal{P}(\eta)_{j}^{-1}\mathbf{v}_{j},$$
  
$$\mathbf{r}_{j} = \mathbf{v}_{j} - \mathcal{B}\mathcal{P}_{j}^{-1}\mathbf{v}_{j}.$$

Imposing 
$$\mathbf{r}_{j}^{(\eta)} = \gamma \mathbf{r}_{j}$$
 yields:  
 $(\mathcal{B} - \eta I) \mathcal{P}(\eta)_{i}^{-1} \mathbf{v}_{i} = \gamma \mathcal{B} \mathcal{P}_{i}^{-1} \mathbf{v}_{i} - (\gamma - 1) \mathbf{v}_{i}$ 



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which yields:

$$\underline{\mathbf{H}}_{m}^{(\eta)} = (\underline{\mathbf{H}}_{m} - \underline{\mathbf{I}}_{m})\,\mathbf{\Gamma}_{m} + \underline{\mathbf{I}}_{m},$$

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## Summary: Nested FOM-FGMRES

In nested FOM-FGMRES, we solve the following (small) optimization problem,

$$\begin{aligned} \mathbf{x}_{m}^{(\eta)} &= \operatorname*{argmin}_{\mathbf{x}\in\widehat{\mathcal{V}}_{m}} \|\mathbf{b} - (\mathcal{B} - \eta I)\mathbf{x}\| \\ &= \operatorname*{argmin}_{\mathbf{y}\in\mathbb{C}^{m}} \|\mathbf{b} - (\mathcal{B} - \eta I)\widehat{\mathcal{V}}_{m}\mathbf{y}\| \\ &= \operatorname*{argmin}_{\mathbf{y}\in\mathbb{C}^{m}} \|\mathbf{b} - \mathcal{V}_{m+1}\underline{\mathbf{H}}_{m}^{(\eta)}\mathbf{y}\| \\ &= \operatorname*{argmin}_{\mathbf{y}\in\mathbb{C}^{m}} \|\beta\mathbf{e}_{1} - \left((\underline{\mathbf{H}}_{m} - \underline{\mathbf{I}}_{m})\Gamma_{m}^{(\eta)} + \underline{\mathbf{I}}_{m}\right)\mathbf{y}\|, \end{aligned}$$

where the entries of  $\Gamma_m^{(\eta)}$  are collinearity factors of inner FOM.



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# Numerical experiments (1/4) as presented in [B./vG., 2014]

Test case from literature:

- $\Omega = [0,1] \times [0,1]$
- *h* = 0.01 implying
  *n* = 10.201 grid points
- system size:
  - 4n = 40.804
- N = 6 frequencies
- point source at center

#### Reference

• T. Airaksinen, A. Pennanen, J. Toivanen, A damping preconditioner for time-harmonic wave equations in fluid and elastic material. Journal of Computational Physics, 2009.





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Numerical experiments (2/4) as presented in [B./vG., 2014]

## Preconditioned **multi-shift GMRES**:

- simultaneous solve
- linear convergence rates

• 
$$\tau = (0.7 - 0.7i)\omega_{max}$$
 ??

• CPU time: 17.71s





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## Numerical experiments (3/4) as presented in [B./vG., 2014]

#### Preconditioned **nested FOM-FGMRES**:

- 20 inner iterations
- truncate when inner residual norm  $\sim 0.1$
- very few outer iterations
- CPU time: 9.12s





# Numerical experiments (4/4) as presented in [B./vG., 2014]

#### Various combinations of nested algorithms:

	multi-shift Krylov methods			
	msGMRES	rest_msGMRES	QMRIDR(4)	msIDR(4)
# inner iterations	-	20	-	-
# outer iterations	103	7	136	134
CPU time	17.71s	6.13s	22.35s	22.58s
	nested multi-shift Krylov methods			
	FOM-FGMRES	IDR(4)-FGMRES	FOM-FQMRIDR(4)	<pre>IDR(4)-FQMRIDR(4)</pre>
# inner iterations	20	25	30	30
# outer iterations	7	9	5	15
CPU time	9.12s	32.99s	8.14s	58.36s



Krylov methods for shifted linear systems

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## Conclusions and future work

- ✓ Inner-outer Krylov methods for Ax = b are widely used → We present an extension to shifted linear systems
- ✓ The shifted Laplace preconditioner is applied as a *first layer*
- ? Future work: 3D problems
  - discretization using TU/e package nutils (high-order FEM)
  - approximate shifted Laplacian with AGMG
  - nested solver in Fortran90





## Thank you for your attention!

#### Further reading:

M. Baumann and M. B. van Gijzen. *Nested Krylov methods for shifted linear systems.* SIAM Journal on Scientific Computing (SISC), Special Issue Copper Mountain Conference 2014 [in press].

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